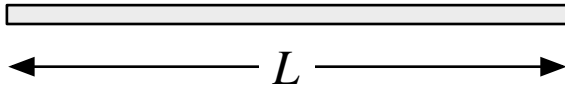


# Integrating to get the rotational inertia of a rod around its end.

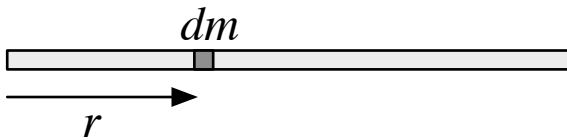
rod with uniform mass per length  $\rho$



$$\rho = \frac{M}{L}$$

$$\rho L = M$$

$$\rho dr = dm \quad (\text{infinitesimally thin piece } dm)$$



$$I = \int r^2 dm \quad (\text{definition of rotational inertia})$$

$$I = \int_0^L r^2 (\rho dr) \quad (\text{substituting from above})$$

$$I = \rho \int_0^L r^2 dr \quad (\text{factor out constant})$$

$$I = \rho \left[ \frac{r^3}{3} \right]_0^L \quad (\text{integrating})$$

$$I = \rho \left[ \frac{L^3}{3} - \frac{0^3}{3} \right] \quad (\text{plugging in limits})$$

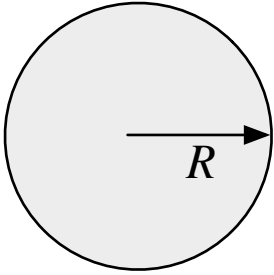
$$I = \frac{\rho L^3}{3}$$

$$I = \frac{(\rho L) L^2}{3} \quad (\text{mass per unit length times total length is total mass})$$

$$I = \frac{ML^2}{3}$$

# Integrating to get the rotational inertia of a disk around its center.

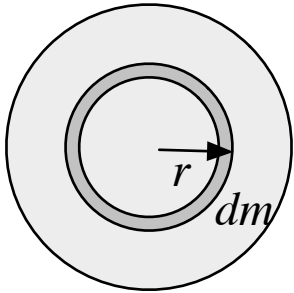
disk with uniform mass per area  $\rho$



$$\rho = \frac{M}{A}$$

$$\rho A = M$$

$$\rho \pi R^2 = M$$



$$\rho 2\pi r dr = dm \quad (\text{infinitesimally thin ring of mass } dm)$$

$$I = \int r^2 dm \quad (\text{definition of rotational inertia})$$

$$I = \int_0^R r^2 (\rho 2\pi r dr) \quad (\text{substituting from above})$$

$$I = \rho 2\pi \int_0^R r^3 dr \quad (\text{factor out constants})$$

$$I = \rho 2\pi \left[ \frac{r^4}{4} \right]_0^R \quad (\text{integrating})$$

$$I = \rho 2\pi \left[ \frac{R^4}{4} - \frac{0^4}{4} \right] \quad (\text{plugging in limits})$$

$$I = \frac{\rho 2\pi R^4}{4}$$

$$I = \frac{2(\rho \pi R^2) R^2}{4} \quad (\text{mass per unit area times total area is total mass})$$

$$I = \frac{MR^2}{2}$$